## **AMENDMENTS TO THE CLAIMS**

10. (Currently amended) An automated cap transfer system comprising:

a horizontal bar coupled to a main support bar by a vertical lead screw, whereby operation of the lead screw actuates a vertical displacement of the horizontal bar relative to the support bar;

a fork coupled to the horizontal bar, the fork having two or more arms for engaging a LCM laser capture microdissection cap;

a pivotable weight coupled to the horizontal bar, wherein the weight is seated on an engaged LCM laser capture microdissection cap;

a lever coupled to the horizontal bar, the lever comprising at least one pin for engaging the weight and a pivot axis;

a kick bar coupled to the support bar, whereby lowering the horizontal bar causes the kick bar to engage the lever and actuate a pivot of the lever about the pivot axis thereby causing the at least one pin of the lever to engage the weight and displace the weight relative to the cap.

- 11. (Original) The system of claim 10, wherein the horizontal bar is further coupled to a horizontal lead screw for actuating a lateral translation of the bar relative to the support bar.
- 12. (Original) The system of claim 11, wherein a lateral translation of the horizontal bar further actuates a retraction of the fork.
- 13. (Original) The system of claim 10, further comprising: a spring for coupling the horizontal bar to the lever.
- 14. (Original) The system of claim 13, further comprising:

a second pin in the lever for engaging the weight such that, when the weight engages the second pin, a force of the spring is transmitted to counteract the weight.

15. (Original) The system of claim 10, wherein the horizontal bar is further coupled to a horizontal lead screw for actuating a lateral translation of the bar relative to the support bar.